Discrepancy-based Inference for Intractable Generative Models using Quasi-Monte Carlo

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## **Intractable Generative Models**

- Likelihood function is intractable.
- Sampling is possible.
- $u_i \sim \mathcal{U}([0,1]^s), G_{\theta}(u_i) \sim \mathbb{P}_{\theta}.$
- Examples include VAE, GANs.



#### **Minimum Distance Estimators (MDE)**

- $\{y_j\}_{j=1}^m \stackrel{\text{ID}}{\sim} \mathbb{Q} \in \mathcal{P}(\mathcal{X}).$
- one can construct an estimator through the framework of MDE:

$$\widehat{\theta}_m^{D} = \arg\min_{\theta\in\Theta} D(\mathbb{P}_{\theta}, \mathbb{Q}^m)$$

where  $\mathbb{Q}^m = \frac{1}{m} \sum_{j=1}^m \delta_{y_j}(x)$ .

•  $\mathbb{P}_{\theta}$  is unknown. Require a good approximation  $D(\mathbb{P}_{\theta}^{n}, \mathbb{Q}^{m})$ .



## **Integral Probability Metrics (IPMs)**

• An IPM is a probability metric which takes the form:

$$D_{\mathcal{F}}(\mathbb{P},\mathbb{Q}) := \sup_{f\in\mathcal{F}} \left| \int_{\mathcal{X}} f(x)\mathbb{P}(\mathrm{d} x) - \int_{\mathcal{X}} f(x)\mathbb{Q}(\mathrm{d} x) \right|$$

- Popular metrics include:
  - Maximum Mean Discrepancy (MMD)
  - Wasserstein Distance
- Other popular divergences (not in IPMs) include:
  - Sinkhorn divergence  $S_{c,p,\lambda}$
  - Sliced Wasserstein Distance.



# **Sample Complexity**

Consider *D* is a metric.

- We want  $D(\mathbb{P}_{\theta}, \mathbb{Q}^m)$  but what we can get is  $D(\mathbb{P}_{\theta}^n, \mathbb{Q}^m)$ .
- We could like make  $|D(\mathbb{P}^n_{\theta}, \mathbb{Q}^m) D(\mathbb{P}_{\theta}, \mathbb{Q})|$  to be as small as possible.
- By basic concentration inequality, we know

 $|D(\mathbb{P}^{n}_{\theta},\mathbb{Q}^{m})-D(\mathbb{P}_{\theta},\mathbb{Q}^{m})|\leq D(\mathbb{P}^{n}_{\theta},\mathbb{P}_{\theta})$ 

Sample complexity  $D(\mathbb{P}^{n}_{\theta}, \mathbb{P}_{\theta})$  plays a key role here!

• Issue with Previous Method: Monte Carlo point set only guarantees  $D(\mathbb{P}_{\theta}^{n}, \mathbb{P}_{\theta}) = O_{p}(n^{-1/2}).$ 



## **Enhancing Sample Complexity via Quasi-Monte Carlo**

• QMC: generate a more "diverse" set of samples from the model.



• **IDEA:** *Replace MC points to estimate discrepancies with QMC/RQMC points.* 



#### Numerical Results: Inference for Multivariate g-and-k Models

The generator for g-and-k model is

$$G_{\theta}(u) := \theta_1 + \theta_2 \left( 1 + 0.8 \frac{(1 - \exp(-\theta_3 z))}{(1 + \exp(-\theta_3 z))} \right) (1 + z^2)^{\theta_4} z$$

where  $z = \Sigma^{\frac{1}{2}} \Phi^{-1}(u)^{\top}$ ,  $u \sim \text{Unif}([0, 1]^d)$ .  $\Sigma$  is a symmetric Toepliz matrix with diagonal entries equal to 1 and subdiagonals equal to  $\theta_5$  and  $\Phi^{-1}$  is the inverse CDF of Gaussian.





## More Applications: generative neural network

- Generative models widely used in modern machine learning are parametrized by neural network.
- Consider  $G_{\theta} : \mathcal{U} \to \mathcal{X}$  with  $\mathcal{U} = [0, 1]^2$  and  $\mathcal{X} = [0, 1]^{784}$  (i.e. s = 2 and d = 784) of the form:

$$G_{\theta}(u) = \phi_2(\phi_1(\phi_1(u^{\top}W^1 + b^1)^{\top}W^2 + b^2)^{\top}W^3 + b^3)$$

where  $\theta$  is a parameter vector containing all entries of the weight matrices and

- $\phi_1(x) = \log(\exp(x) + 1)$  (a softplus activation function)
- $\phi_2(x) = (1 + \exp(-x))^{-1}$  (a logistic activation function)



#### More Applications: generative neural network





## **Theory: Assumptions**

#### Assumption 1(QMC points set)

Given a model  $\mathbb{P}_{\theta}$  with generative process  $(\text{Unif}([0, 1]^s), G_{\theta})$ , we assume we have access to  $x_i = G_{\theta}(u_i)$  for i = 1, ..., n where  $\{u_i\}_{i=1}^n \subset [0, 1]^s$  form a QMC or RQMC point set for some  $\alpha_s > 0$ . Furthermore, we write  $\mathbb{P}_{\theta}^n = \frac{1}{n} \sum_{i=1}^n \delta_{x_i}$ .

#### Assumption 2(Smoothness condition)

Assume that the domain  $\mathcal{X} \subset \mathbb{R}^d$  is a compact space and that the generator is a map  $G_\theta : [0,1]^s \to \mathcal{X}$  where:

- 1.  $\partial^{(1,...,1)}(G_{\theta})_{j} \in \mathcal{C}([0,1]^{s})$  for all j = 1,...,d.
- 2.  $\partial^{\nu}(G_{\theta})_{j}(\cdot : 1_{-\nu}) \in L^{p_{j}}([0,1]^{|\nu|})$  for all  $j = 1, \ldots, d$  and  $\nu \in \{0,1\}^{s} \setminus (0,\ldots,0)$ , where  $p_{j} \in [1,\infty]$  and  $\sum_{j=1}^{d} p_{j}^{-1} \leq 1$ .



#### **Theory: Results**

**Theorem** Let  $k \in C^{s,s}(\mathcal{X})$ ,  $\mathbb{P}_{\theta} \in \mathcal{P}_k$  and suppose Assumptions 1-2 hold. Then,

 $\mathrm{MMD}(\mathbb{P}_{\theta},\mathbb{P}_{\theta}^{n})=O(n^{-1}(\log n)^{\alpha_{s}}).$ 

**Corollary** Suppose the conditions in above Theorem hold. Then,

 $|\mathrm{MMD}(\mathbb{P}_{\theta},\mathbb{Q}^m)-\mathrm{MMD}(\mathbb{P}_{\theta}^n,\mathbb{Q}^m)|=O(n^{-1}(\log n)^{\alpha_s}).$ 



#### **More Details**

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